Synthetic Stereoscopic Panoramic Images

What are they? How are they created? What are they good for?

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Introduction & Motivation

- Familiar with QuickTime VR and many derivatives.
- Cylindrical panoramic projections.
- Applications in virtual environments and interactive cinema.
- Suited also to data visualisation where realtime graphics isn't possible and/or the desired render quality is high.
- Stereoscopic panoramic images support the two features of the human visual system not normally present in computer displays: peripheral vision and stereopsis.

Camera model: monoscopic panoramic

- Single rotating slit camera
- Approximations using stitching work OK for monoscopic images but not stereoscopic.
- Rotating two cameras independently about their centers obviously doesn't give a stereoscopic panoramic pair.



Camera model: stereoscopic panoramic pair



- Twin rotating slit camera. Copes with movement in the scene.
- Usually possible to script most rendering packages to achieve this.
- Real cameras exist, for example the Roundshot, continuous capture onto 70mm film.



Example: Hampi (India)



Roundshot VR camera.

PLACE-Hampi: Sarah Kenderdine, Jeffrey Shaw & John Gollings Icinema, UNSW

- 10,000+ pixels across, drum scanned.
- Between 1000 to 4000 pixels high depending on the lens.
- Requires alignment and edge blending post processing.

CG: Slit rendering



 Combine many narrow perspective projections: eg: 1 degree horizontally by 90 degrees vertically.

Camera rotates in steps of the horizontal aperture for a perfect stitch.

Test image



POVRay

Example: Royal Exhibition Building



3D StudioMax

Suzanne Bekhit, Amanda Kuek, Handa Lie

Stereoscopic matching: Film & CG

- Combining photographic & synthetic (compositing), more difficult for stereoscopic content. In traditional compositing, even of 3D content, there is less depth perception.
- Matching field of view vertically, determines aspect of panorama image.
- Determine strip width (w) in pixels, determines panoramic width (W).
- Horizontal aperture needs to be an integer divisor of 360 degrees.
- Match the eye/camera separation, not necessarily the human eye separation.
- Lens correction of film or lens warping of CG?
 Lens distortion is only in the vertical direction.
- Matching/setting the distance to zero parallax.

m. $w = W \phi_h / 360$ $x. \qquad \phi_v = 2 \operatorname{atan}(H \pi / W)$ $H \tan(\phi_h / 2) = w \tan(\phi_v / 2)$

Precise matching of parallax

Ganesha



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right camera panorama

Zero parallax can be set in post production or preferably in the playback software by sliding images horizontally with respect to each other, wrapping at the left/right boundary.

No magic, given the characteristics of the cameras we can determine shift by D pixels to give a particular zero parallax distance fo.

 $D = W \phi / (2\pi) = W asin(r / f_o) / \pi$



9216 x 1024 pixels



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Projection Environments

- Flat display screen(s) or wall(s).
- While movie is running you can zoom/rotate.
- Full cylindrical environments, AVIE (ICinema).
- Geometry correction and edgeblending of 6 pairs of SXGA+ projectors (1400x1050), 12 projectors in total.
- Stereoscopic dome.
- Ideal strategy would be to keep all stereoscopic pairs with zero parallax at infinity (parallel cameras) and apply desired zero parallax within the playback software.



Icinema, UNSW



Summary

- Succeeded in creating comfortable viewing stereoscopic panoramic pairs.
- Developed techniques to create synthetic panoramic and composite with photographic panoramic pairs with correct and matching depth relationships.
- Technique applies equally to rendered (raytraced) content as well as interactive (OpenGL) content using multipass texture approach.
- Developed software that presents stereoscopic panoramic images on flat screen or in a full cylinder (later requires geometry correction and edge blending).
- Has been extended to display stereoscopic panoramic movies (ICinema, UNSW).

Questions?